





Product Segments

Industrial Motion

TiMOTION's JP3 series inline linear actuator was designed for low load industrial applications where up to IP69K dust and liquid ingress protection is necessary. It is best suited for applications with aesthetic or compact installation dimension requirements. Hall sensors are optional for the JP3 which allow for synchronization and position feedback.

General Features

Voltage of motor 12V DC or 24V DC Maximum load 2,000N in push/pull

Maximum speed at full load 20.0mm/s (with 500N in a push or pull

condition)

Standard stroke 20~500mm

Minimum installation dimension Stroke+217mm

IP rating Up to IP69K

Color Black or grey

Certificate ES60601-1 and IEC60601-1 compliant

Operational temperature range -5°C~+70°C An inline actuator designed for small spaces



Load and Speed

| CODE | Load (N) | | Self | Typical Curr | ent (A) | Typical Spe | ed (mm/s) | Noise |
|----------|------------|------------------------------------------------------|---------------------|-------------------|---------------------|-------------|-----------|-------|
| | Push | h Pull Locking No Load With Load Force 32V DC 24V DC | With Load 24V DC | No Load 32V DC | With Load 24V DC | (db) | | |
| Motor Sp | eed (5600R | PM) | | | | | | |
| В | 2000 | 2000 | 2000 | 1.0 | 3.0 | 10.0 | 4.2 | ≤ 65 |
| С | 1500 | 1500 | 1500 | 1.0 | 3.0 | 14.0 | 6.5 | ≤ 65 |
| D | 1000 | 1000 | 1000 | 1.0 | 3.0 | 20.5 | 9.5 | ≤ 65 |
| E | 500 | 500 | 500 | 1.0 | 3.0 | 35.0 | 20.0 | ≤ 65 |

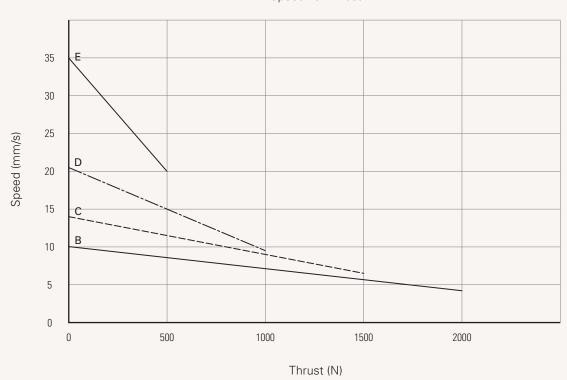
Note

- 1 With motor 12V current is around 2 times in 24V; speed around the same.
- 2 Self locking force: Tested average value when working with TiMOTION control system in push direction.
- 3 Environmental noise \leq 38db.

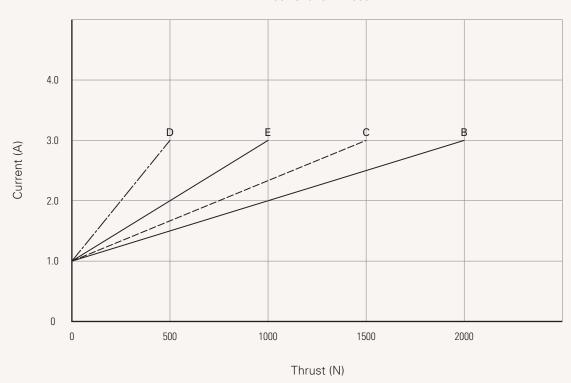


Motor Speed (5600RPM)

Speed vs. Thrust



Current vs. Thrust



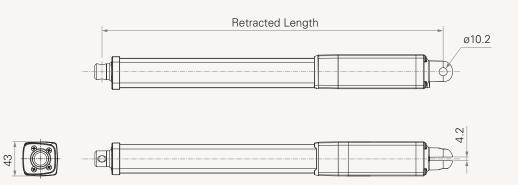
Note

1 The performance data in the curve charts shows theoretical value only.



Drawing

Standard Dimensions (mm)



Wire Definitions

| CODE* | Pin | | | | | |
|-------|---------------|---------------|---------------------|---------------------|----------------|--------------------|
| | 1 | 2 | 3 | 4 | 5 | 6 |
| | (green) | (red) | (white) | (black) | (yellow) | (blue) |
| 1 | extend (VDC+) | N/A | N/A | N/A | retract (VDC+) | N/A |
| 2 | extend (VDC+) | N/A | middle switch pin B | middle switch pin A | retract (VDC+) | N/A |
| 3 | extend (VDC+) | common | upper limit switch | N/A | retract (VDC+) | lower limit switch |
| 4 | extend (VDC+) | common | upper limit switch | medium limit switch | retract (VDC+) | lower limit switch |

Note

* See ordering key - functions for limit switches



Retracted length (mm)

- 1. Calculate A+B+C=Y
- 2. Retracted length needs to \geq Stroke+Y

| A. Attachment | Rear Attachment Code |
|-----------------------|----------------------|
| Front Attachment Code | 1 |
| 1 | +217 |
| 2 | +217 |
| 3 | +230 |
| 4 | +230 |
| 5 | +230 |

| B. Stroke (mm) | | |
|----------------|-----|--|
| 20~150 | - | |
| 151~200 | - | |
| 201~250 | +5 | |
| 251~300 | +10 | |
| 301~350 | +15 | |
| 351~400 | +20 | |

For stroke over 400mm, +5mm for each incremental 50mm stroke.

| C. Output Signals | |
|-------------------|-----|
| Code | |
| 0 | - |
| 1 | +13 |
| 2 | +13 |



JP3 Ordering Key



| | | | | Version | | | | |
|------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------|--|--|--|--|
| Voltage | 1 = 12V | 2 = 24V | 5 = 24V, PTC | | | | | |
| Load and Speed | See page 2. | | | | | | | |
| Stroke (mm) | _ | | | | | | | |
| | | | | | | | | |
| Retracted Length mm) | See page 5. | | | | | | | |
| | | | | | | | | |
| Rear Attachment | 1 = Aluminum casting, | Clevis: U, Slot: 4.2mm, Depth: 18 | mm, Hole: 10.2mm | | | | | |
| Front Attachment | 1 = Aluminum casting, Hole: 6.4mm | | | | | | | |
| | 2 = Aluminum casting, Hole: 8mm | | | | | | | |
| | 3 = Aluminum casting, Clevis: U, Slot: 6mm, Depth: 13mm, Hole: 10mm | | | | | | | |
| | | Clevis: U, Slot: 6mm, Depth: 13mn | | | | | | |
| | | Clevis: U, Slot: 6mm, Depth: 13mn | | | | | | |
| Direction of Rear Attach | ment (Counterclockwis | 1 = 0° | | | | | | |
| Color | 1 = Black | | 2 = Grey (Pantone 428 | C) | | | | |
| P Rating | 1 = Without | 3 = IP66 | 6 = IP66D | 8 = IP69K | | | | |
| | 2 = IP54 | 5 = IP66W | 7 = IP68 | | | | | |
| | 0 = Without (standard) | | | | | | | |
| | | | | 1 = Two switches at full retracted/extended positions to cut current | | | | |
| Spindle Sub-Assembly | 1 = Two switches at ful | II retracted/extended positions to o | cut current | | | | | |
| Spindle Sub-Assembly Functions for | | II retracted/extended positions to o | | ınal | | | | |
| Spindle Sub-Assembly | 2 = Two switches at ful | | cut current + 3rd LS to send sig | ınal | | | | |
| Spindle Sub-Assembly | 2 = Two switches at full 3 = Two switches at full | II retracted/extended positions to d | cut current + 3rd LS to send sig send signal | | | | | |
| Spindle Sub-Assembly Functions for Limit Switches | 2 = Two switches at full 3 = Two switches at full | II retracted/extended positions to o | cut current + 3rd LS to send sig send signal | | | | | |
| Spindle Sub-Assembly Functions for Limit Switches Output Signals | 2 = Two switches at ful 3 = Two switches at ful 4 = Two switches at ful | II retracted/extended positions to a 1 = One Hall sensor | cut current + 3rd LS to send sig send signal send signal + 3rd LS to send sig | | | | | |
| Special Functions for Spindle Sub-Assembly Functions for Limit Switches Output Signals Connector Cable Length | 2 = Two switches at ful 3 = Two switches at ful 4 = Two switches at ful 0 = Without | II retracted/extended positions to a 1 = One Hall sensor | cut current + 3rd LS to send sig send signal send signal + 3rd LS to send sig 2 = Two Hall sensors | | | | | |

Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application. TiMOTION products are subject to change without prior notice.

